

RM08

Miniature Rotary Magnetic encoder

The RM08 is a compact, sealed, high-speed magnetic encoder designed for use in space-constrained applications. The non-contact two-piece design eliminates the need for seals or bearings and ensures long-term reliability and easy installation.

Designed for direct integration into high-volume OEM applications, the RM08 encoder can be used in a variety of applications including motor control and industrial automation. The encoder housing has a diameter of only 8 mm and offers a degree of protection to IP68.

SUPER SMALL
SIZE

HIGH SPEED

EASY
INSTALLATION



Features and benefits

- ▶ Super small – 8 mm diameter
- ▶ Non-contact, frictionless design
- ▶ High-speed operation up to 30,000 rpm
- ▶ Accuracy up to $\pm 0.3^\circ$
- ▶ Resolutions up to 12 bit
- ▶ Analogue sinusoidal, incremental, SSI and linear voltage output formats



MOTOR CONTROL



MEDICAL



PAN/TILT POSITIONING



GRIPPER



INDUSTRIAL AUTOMATION

General information

The encoder consists of a magnet/ magnetic actuator and a separate sensor board. The rotation of the magnetic actuator is sensed and processed by a custom encoder chip in the body, to provide analogue, incremental, SSI or linear voltage outputs. The RM08 encoders use the AM4096 sensor, see [the AM4096 data sheet](#) for details.

RM08 readhead



+

Magnet



=

RM08 system



Product range

RM08AC

Analogue sinusoidal output with a single sine/cosine period per revolution.

RM08I

Incremental with 8 to 1,024 pulses per revolution (up to 4,096 counts per revolution).

RM08S

Synchro serial interface (SSI) with up to 4096 positions per revolution.

RM08Vx

Linear voltage output in a range of variants.

Storage and handling

Operating and storage temperature

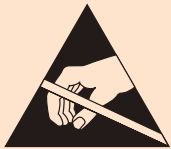
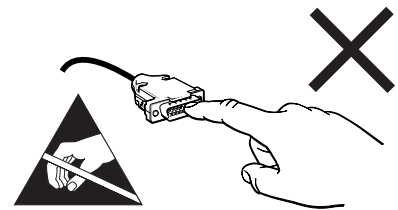
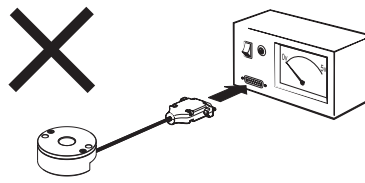
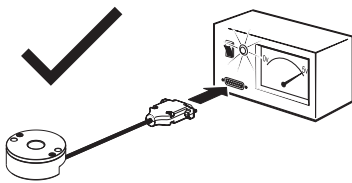


–40 °C to +85 °C
–25°C to +85°C (limited by LD boards for IC and SC output)

Humidity



Up to IP68



Readhead is ESD sensitive - handle with care.

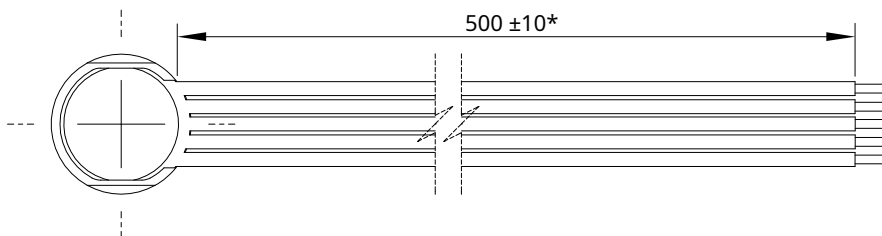
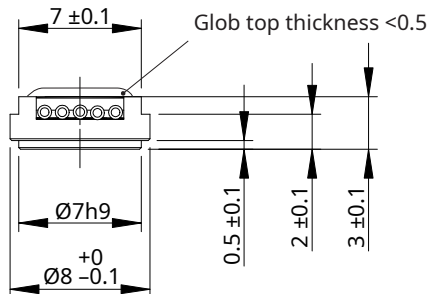
Do not touch electronic circuit, wires or sensor area without proper ESD protection or outside of ESD controlled environment.

Packaging

Each encoder is packed individually in an antistatic bag.

Dimension drawings

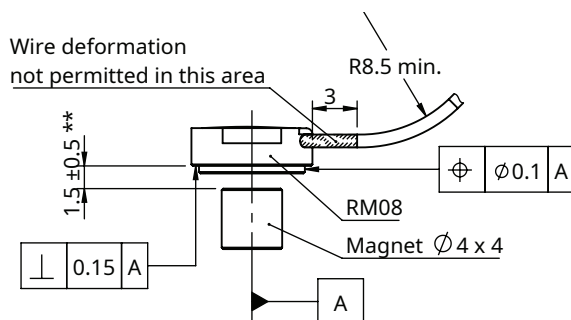
Dimensions and tolerances are in mm. Dimensions without tolerance values are in accordance with ISO 2768-m.



* For cable lengths over 0.5 m, see [FAQ](#).

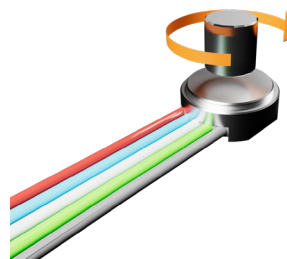
The number of wires depends on the output type.

Installation drawing



** 1 mm ± 0.2 mm for Ø3 × 1 mm magnet

For more information see [Part numbering](#).

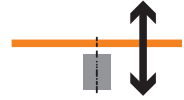


Clockwise rotation of magnet.

Installation tolerances

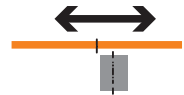
Mounting distance

See installation drawings of encoder assemblies on [page 4](#).



Radial displacement (concentricity)

±0.1 mm



— - Encoder ■ - Magnet

Technical specifications

Mechanical data

Encoder housing material	Aluminium
Encoder mass	<2 g (with 200 mm long wires)
Wire thickness	AWG30
Magnet material	SmCo (Sm ₂ Co ₁₇), NiCuNi coated
Magnet mass	0.4 g
Shock	Half-sine 100 g, according to IEC 60068-2-27, Ed. 4
Steady-state acceleration	700 g, according to IEC 60068-2-27, Ed. 2

Environmental data

Temperature	Operating	-40 °C to +85 °C
	Storage	-40 °C to +85 °C
Environmental sealing	IP68*	

* IP protection is ensured only when a mating connector with an equal or higher IP rating is used.

Electrical connections

Output type							
AC		ID		SD		Vx	
Signal	Wire colour	Signal	Wire colour	Signal	Wire colour	Signal	Wire colour
V _{dd}	Red	V _{dd}	Red	V _{dd}	Red	V _{dd}	Red
GND	Blue	GND	Blue	GND	Blue	GND	Blue
Sin	White	Z	White	Clock	White	V _{out}	Green
Cos	Grey	B	Green	Data	Green		
		A	Grey				

Output type			
IC (LDB01)		SC (LDB02)	
			
Pin nr.	Signal	Pin nr.	Signal
1	A+	1	V _{dd}
2	A-	2	GND
3	B-	3	Data+
4	B+	4	Data-
5	Z+	5	CLK-
6	Z-	6	CLK+
7	GND		
8	V _{dd}		

Output types

AC – Analogue sinusoidal outputs

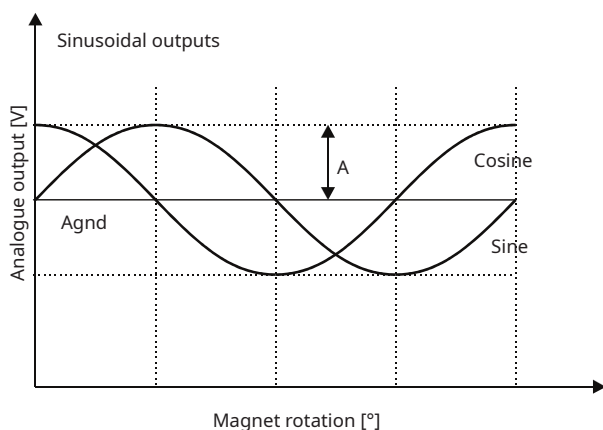
2 channels V_A V_B sinusoids (90° phase shifted, single ended)

Specifications

Power supply	$V_{dd} = 5\text{ V or } 3.3\text{ V} \pm 5\%$	
Current consumption	Typ. 26 mA	
Outputs	Signal amplitude (A)*	0.8 V ± 0.2 V
	Signal offset (Agnd)	1.55 V ± 5 mV
	Phase difference	90° $\pm 0.2^\circ$
Maximum speed	30,000 rpm	
Operating temperature	-40 °C to +85 °C	

* Valid for $\varnothing 4 \times 4$ mm magnets only

Timing diagram for clockwise rotaion of magnet



IC – Incremental, RS422

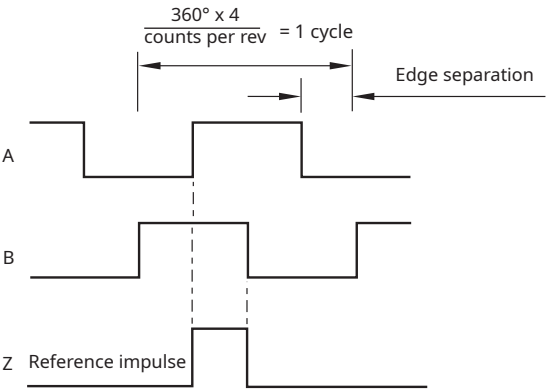
Square wave differential line driver to RS422

Specifications

Power supply	$V_{dd} = 5\text{ V or } 3.3\text{ V} \pm 5\%$
Current consumption	Typ. 26 mA
Output signals	A, B, Z, A-, B-, Z- (RS422)
Accuracy*	Typ. $\pm 0.3^\circ$
Hysteresis	0.17°
Resolution	32, 64, 128, 256, 512, 1024, 2048, 4096 cpr
Maximum speed	30,000 rpm
Operating temperature	$-25\text{ }^\circ\text{C to } +85\text{ }^\circ\text{C}$ (limited by LDB01)

* Valid for $\varnothing 4 \times 4\text{ mm}$ magnets only.

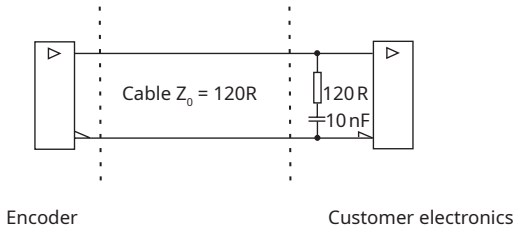
Timing diagram



B leads A for clockwise rotation of magnetic actuator.

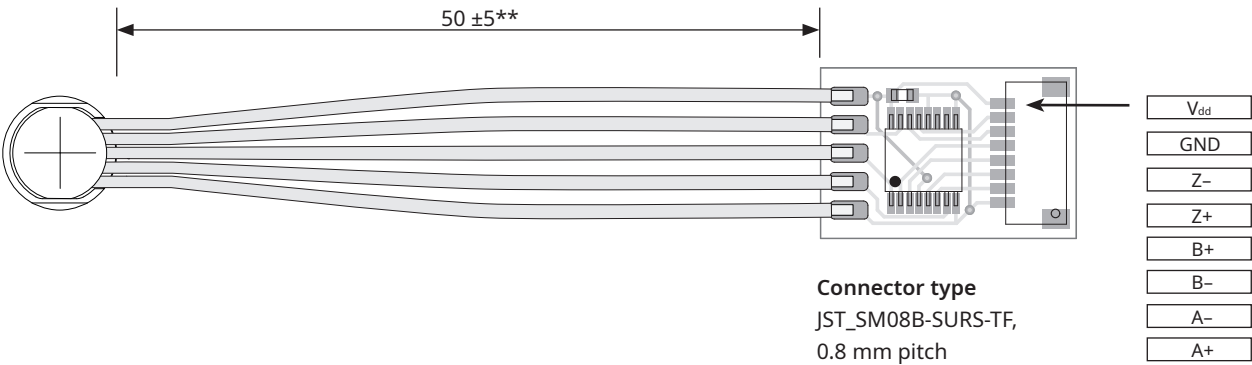
Recommended signal termination

For data output lines only



RM08 with line driver board (LDB01)

Dimensions and tolerance in mm



** Differential output available with soldered LDB01 and added strain relief on 50 mm distance from the RM08.

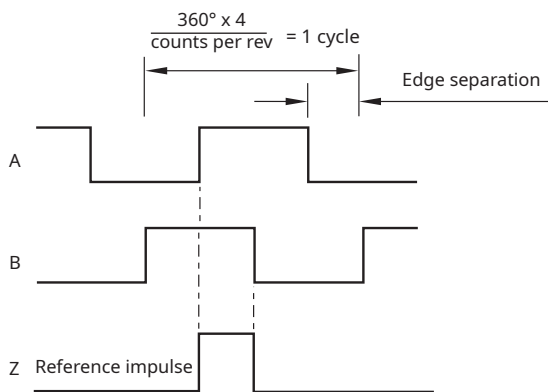
ID – Incremental, single-ended, 5 V

Specifications

Power supply	$V_{dd} = 5\text{ V or } 3.3\text{ V} \pm 5\%$
Current consumption	Typ. 26 mA
Output signals	A, B, Z (single-ended)
Accuracy*	Typ. $\pm 0.3^\circ$
Hysteresis	0.17°
Resolution	32, 64, 128, 256, 512, 1024, 2048, 4096 cpr
Maximum speed	30,000 rpm
Operating temperature	$-40\text{ }^\circ\text{C to } +85\text{ }^\circ\text{C}$

* Valid for $\varnothing 4 \times 4\text{ mm}$ magnets only.

Timing diagram



B leads A for clockwise rotation of magnetic actuator.

SC – Absolute binary synchro-serial interface (SSI)

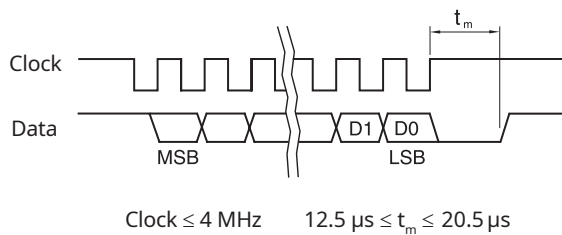
Serial encoded absolute position measurement

Specifications

Output code	Natural binary
Power supply	$V_{dd} = 5\text{ V or } 3.3\text{ V} \pm 5\%$
Current consumption	Typ. 26 mA
Data output	Serial data (RS422)
Data input	Clock (RS422)
Clock frequency	$\leq 4\text{ MHz}$
Accuracy*	Typ. $\pm 0.3^\circ$
Hysteresis	0.17°
Resolution	32, 64, 128, 256, 512, 1024, 2048, 4096 cpr
Maximum speed	30,000 rpm
Operating temperature	$-25\text{ }^\circ\text{C to } +85\text{ }^\circ\text{C}$ (limited by LDB02)

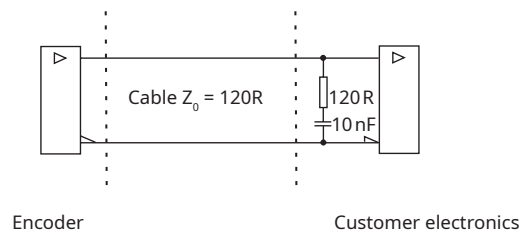
* Valid for $\varnothing 4 \times 4\text{ mm}$ magnets only.

Timing diagram



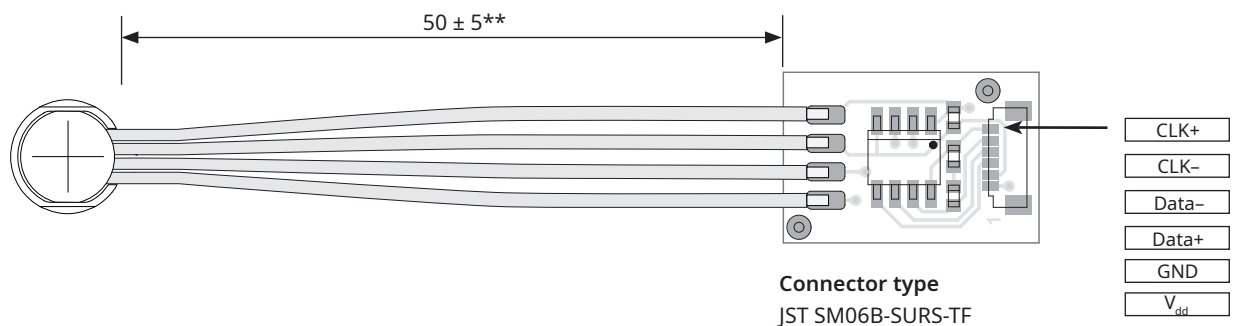
Recommended signal termination

For data output lines only



RM08 with line driver board (LDB02)

Dimensions and tolerance in mm



** Differential output available with soldered LDB02 and added strain relief on 50 mm distance from the RM08.

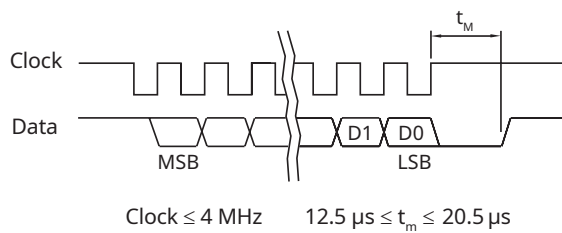
SD – Absolute binary synchro-serial interface (SSI)

Specifications

Output code	Natural binary
Power supply	$V_{dd} = 5\text{ V or }3.3\text{ V} \pm 5\%$
Current consumption	Typ. 26 mA
Data output	Data (single ended)
Data input	Clock (single ended)
Clock frequency	$\leq 4\text{ MHz}$
Accuracy*	Typ. $\pm 0.3^\circ$
Hysteresis	0.17°
Resolution	32, 64, 128, 256, 512, 1024, 2048, 4096 cpr
Maximum speed	30,000 rpm
Operating temperature	$-40\text{ }^\circ\text{C to }+85\text{ }^\circ\text{C}$

* Valid for $\varnothing 4 \times 4\text{ mm}$ magnets only.

Timing diagram



Position increases for clockwise rotation of magnetic actuator.

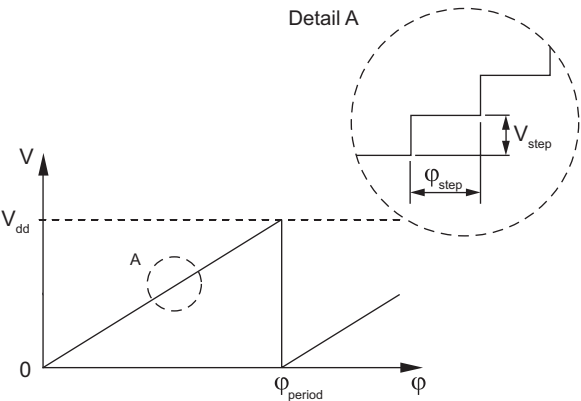
Vx – Linear voltage output

Alternative for potentiometers

Specifications

Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Current consumption	Typ. 26 mA
Output voltage	0 V to V_{dd}
Output loading	Max. 10 mA
Resolution of DAC	10 bit
Nonlinearity	1 %
Maximum speed	30,000 rpm
Operating temperature	-40 °C to +85 °C

Timing diagram



φ_{period}	N_{period}	N_{step}	φ_{step}
360°	1	1,024	0.35°
180°	2	1,024	0.18°
90°	4	1,024	0.09°
45°	8	512	0.09°

$$\varphi_{\text{step}} = \frac{\varphi_{\text{period}}}{N_{\text{step}}} \quad V_{\text{step}} = \frac{V_{dd}}{N_{\text{step}}}$$

- φ_{period} = Angle covered in one period (one sawtooth)
- V_{period} = Output voltage range for one period
- φ_{step} = Step angle (angular movement needed to register a change in the position)
- V_{step} = Output voltage range for one step
- N_{period} = Number of periods in one revolution
- N_{step} = Number of steps in one period

Output type and electrical variant

Rotation \ φ_{period}	360°	180°	90°	45°
Clockwise	VA	VB	VC	VD
Counterclockwise	VE	VF	VG	VH

Part numbering

RM08 ID 00 12B 02 L 2 G 00

Output type

AC - Analogue sinusoidal

IC - Incremental, RS422 *

ID - Incremental, single ended

SC - Absolute binary synchro-serial (SSI), RS422 *

SD - Absolute binary synchro-serial (SSI), single ended

Vx - Linear voltage output 0 - 5 V, supply 5 V DC:

	360°	180°	90°	45°
CW	VA	VB	VC	VD
CCW	VE	VF	VG	VH

Shaft size

00 - N/A (standard)

Resolution

For AC:

01S - One sine/cosine period per revolution

For IC, ID, SC and SD (counts/positions per revolution):

Binary		
12B - 4096	09B - 512	06B - 64
11B - 2048	08B - 256	05B - 32
10B - 1024	07B - 125	

For Vx:

10B - 1024 counts/positions per revolution

Cable length (length of leads)

02 - 0.2 m (max. 0.5 m) (for AC, ID, SD and Vx only)

50 - 50 mm (for IC and SC only)

For cable lengths above 0.5 m, see [FAQ](#).

Connector

L - Leads only (no connector)

U - Line driver board with JST connector

Body style and cable exit

2 - Cylindrical body, radial cable/leads exit

Environment and material

G - IP68, no EMC grade, aluminium body (standard)

Special requirements

00 - No special requirements (standard)

33 - 3.3 V power supply

* Differential output available with soldered LDB01/LDB02 and added strain relief on 50 mm distance from the RM08. See image below.

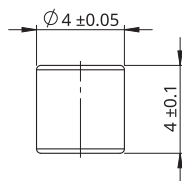


Table of available combinations

Series	Output type	Shaft size	Resolution	Cable length	Connector	Body style and cable exit	Environment and material	Special requirements
RM08	AC	00	01S	02	L	2	G	00 / 33
	IC		05B / 06B / 07B / 08B / 09B / 10B / 11B / 12B	50	U			
	ID			02	L			
	SC			50	U			
	SD			02	L			
	Vx		10B		00			

Magnetic actuator and magnet ordering information

Magnet for direct recessing in non-ferrous shafts



Fixing: Adhesive (recommended – LOCTITE 648 or 2701)

Part numbers:

For resolutions up to 9 bit absolute (512 cpr incremental)

RMM44A2A00 (individually packed) – for sample quantities only

RMM44A2C00 (packed in tubes)

For resolutions from 10 bit absolute (800 cpr incremental) and above

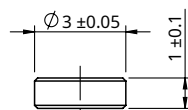
RMM44A3A00 (individually packed) – for sample quantities only

RMM44A3C00 (packed in tubes)

Part numbers:

RMM3010A1B00

RMM3010 magnets are only tested (not graded). Specified accuracy cannot be achieved by using magnet RMM3010



Accessories

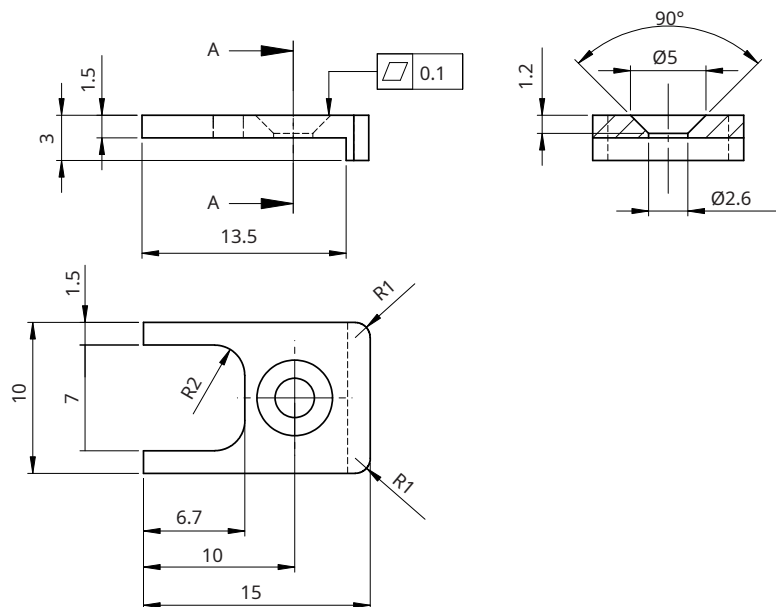
Mounting bracket



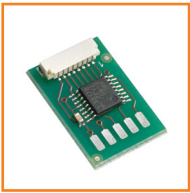
ACC014

Dimensions

Dimensions and tolerances are in mm.



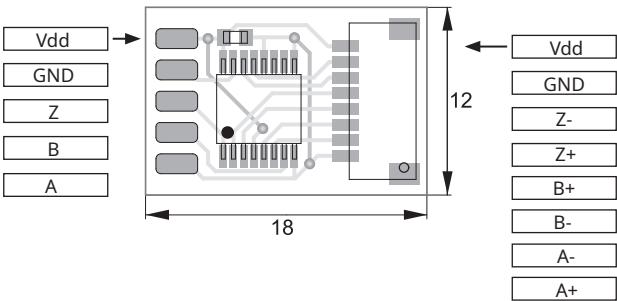
Line drive board for incremental output - LDB01



LDB01

Dimensions

Dimensions and tolerances are in mm.



Cable assembly for LDB01



ACC033, ACC034

Cable specifications

M-9693-2350-01-C

Configuration

10 × 0.0320 mm²

Sheath color

Black

Rated voltage

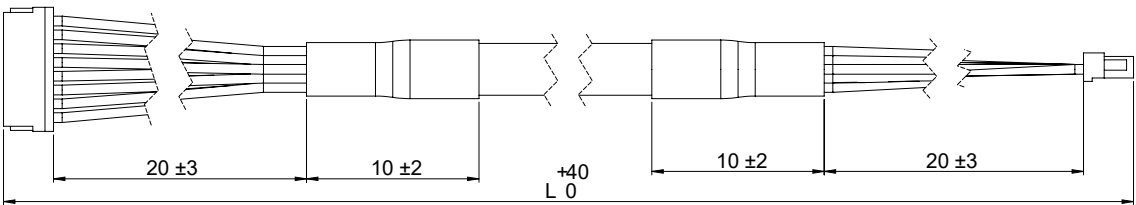
30 V

Temperature range

From -40 °C to +90 °C

Dimensions

Dimensions and tolerances are in mm.



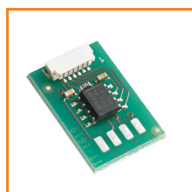
Electrical connections

Pin	Wire color
1	Grey
2	Pink
3	Yellow
4	Green
5	White
6	Brown
7	Blue
8	Red

Part number

	Cable length (L)
ACC033	1 m
ACC034	0.5 m

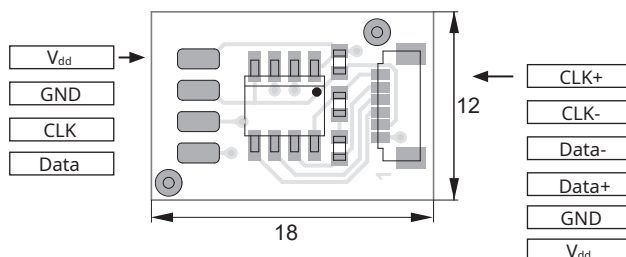
Line drive board for SSI output - LDB02



LDB02

Dimensions

Dimensions and tolerances are in mm.



Cable assembly for LDB02



ACC031, ACC032

Cable specifications

M-9693-2350-01-C

Configuration

10 × 0.0320 mm²

Sheath color

Black

Rated voltage

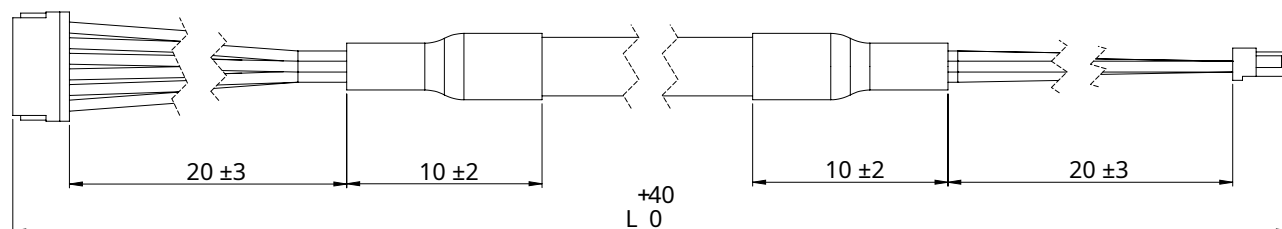
30 V

Temperature range

From -40 °C to +90 °C

Dimensions

Dimensions and tolerances are in mm.



Electrical connections

Pin	Wire color
1	Red
2	Blue
3	Green
4	Yellow
5	Brown
6	White

Part number

	Cable length (L)
ACC031	1 m
ACC032	0.5 m

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Document issues

Issue	Date	Page	Description
16	29. 5. 2025	General	New design of document, dimension drawing amended
17	24. 11. 2025	4	Installation drawing ride height amended
18	5. 2. 2026	13	Part numbering amended

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